Manav Gagvani - Senior Research Notes

* Manav shouldn’t laugh as much
* Forgot to mention last bullet in intro
* Billion or trillion?
* Put supervised learning in the context of self-driving. Why is reinforcement different in the context of self driving, not agent.
* Acceleration and velocity are not key metrics, they are observations.
* PPO is for continuous domain, contrast with the alternative, e.g. discrete values such as specific angles.
* 921K values, not three times that.
* Sip water in between slides
* With 32 numbers any possible picture (not pic, but representation with salient info such as centerline, minus shadows and glare)
* Plot - labels for each axis.
* Simulation vs. Reality : label the axes
* Pace was good and it is not too fast or too slow, content is understandable and makes sense
* Gesturing excessively
* Less hand waving